

ABSTRACT

A device operates at an outlet channel of a feeder, where objects are conveyed, arranged in the same way and in a row one after another, for withdrawing single objects and for regularly spacing out the objects on carriers catching each time the foremost object of the row of objects. A driver moves the carriers through a terminal section of the channel to catch the foremost object. A conveyor conveys the withdrawn objects for directing and spacing out the objects along a conveying direction and for conveying the equidistant objects to a robotized manipulation station.